Nonlinear and Optimal Control Systems

Description: Designed for one-semester introductory senior-or graduate-level course, the authors provide the student with an introduction of analysis techniques used in the design of nonlinear and optimal feedback control systems. There is special emphasis on the fundamental topics of stability, controllability, and optimality, and on the corresponding geometry associated with these topics. Each chapter contains several examples and a variety of exercises.

Contents: Nonlinear Dynamical Systems.
Nonlinear Control Systems.
Nonlinear Optimization.
Lyapunov Stability.
Lyapunov Control System Design.
Controllability of Nonlinear Systems.
Optimal Control Systems.
Optimal Control Design.
Differential Games.
References.
Index.

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